## User manual IMB2-2V

## Direct current / direct voltage signals 0-20 mA, 4-20 mA, 0-10 VDC



## Technical features:

- red display of -19999... 99999 digits
- red 55 points bargraph
- adjustable bar or dot operation or operation with permanent display of center point
- min/max memory
- 30 additional adjustable setpoints
- display flashing at threshold value exceedance/undercut
- zero-key for triggering of Hold, Tara
- permanent min/max-value recording
- volume metering (totalisator)
- mathematical functions like reciprocal value, square root, squaring or rounding
- setpoint generator
- sliding averaging
- brightness control
- programming interlock via access code
- protection class IP65 at the front
- plug-in screw terminal
- 2 relay outputs (changer)
- optional: sensor supply and digital input
- optional: analog output
- optional: interfaces RS232 or RS485
- accessories: PC-based configuration kit PM-TOOL with CD and USB-adaptor for devices without keypad and for a simple adjustment of standard devices


## Identification

| STANDARD TYPES | ORDER NUMBER |
| :--- | :---: |
| Direct current / direct voltage | IMB2-2VR5RR.0001.S72AD |
| Housing size: $96 \times 96 \mathrm{~mm}$ | IMB2-2VR5RR.0001.W72A |

## Options - break-down ordering code:



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## 1. Brief description

The panel meter instrument IMB2-2V is a 5 -digit digital display with a 55 points bargraph display and two galvanic isolated setpoints; designed for direct current/direct voltage signals. The configuration happens via four keys at the front. The integrated programming interlock prevents unrequested changes of parameters and can be unlocked again with an individual code. Optional the following functions are available: a supply for the sensor, a digital input for triggering of Hold (Tara), two analog outputs and interfaces for further evaluating in the unit. The electrical connection is done via plug-in terminals on the back side.
Selectable functions like e.g. the recall of the min/max-value, an averaging of the measuring signals, a nominal presetting or setpoint presetting, a direct threshold value regulation during operation mode and further measuring setpoints for linearisation, complete the modern device concept.

## 2. Assembly

Please read the Safety advices on page 37 before installation and keep this user manual for future reference.


1. After removing the fixing elements, insert the device.
2. Check the seal to make sure it fits securely.
3. Click the fixing elements back into place and tighten the clamping screws by hand. Then use a screwdriver to tighten them another half a turn.

CAUTION! The torque should not exceed 0.1 Nm !

Please state you favorite dimension symbol in your order, they can not be exchanged afterwards!

## 3. Electrical connection

Type MB2-2VR5RR.0001.S70AD with a supply of 100-240 VAC Type MB2-2VR5RR.0001.W70AD with a supply of 10-40 VDC


## Options:



## Connection examples

## IMB2-2V devices with current input / voltage

MB2-2V-devices in combination with a
2-wire-sensor 4-20 mA


MB2-2V-devices in combination with a 3 -wire-sensor 0/4-20 mA


MB2-2V-devices in combination with a
3 -wire-sensor 0-10 V


IMB2-2V-devices with current input / voltage input and sensor supply

2-wire-sensor 4-20 mA


3-wire-sensor 0-20 mA


3-wire-sensor $0-10 \mathrm{~V}$


## 4. Description of function and operation

## Operation

The operation is divided into three different levels.

## Menu level (delivery status)

This level was designed for the standard settings of the device. Only menu items which are sufficent to set the device into operation are displayed. To get into the professional level, run through the menu level and parameterise PROF under menu item RUM.

Menu group level (complete function volume)
Suited for complex applications as e.g. linkage of alarms, setpoint treatment, totaliser function etc. In this level function groups which allow an extended parameterisation of the standard settings are availabe. To leave the menu group level, run through this level and parameterise ULOC under menu item RUM.

## Parameterisation level:

Parameter deposited in the menu item can here be parameterised. Functions, that can be changed or adjusted, are always signalised by a flashing of the display. Settings that are made in the parameterisation level are confirmed with [P] and thus saved. Pressing the [O]-key leads to a break-off of the value input and to a change into the menu level. All adjustments are saved automatically by the device and changes into operating mode, if no further key operation is done within the next 10 seconds.

| Level | Key | Description |
| :---: | :---: | :---: |
| Menu-level | P | Change to parameterisation level and deposited values. |
|  | $\triangle \nabla$ | Keys for up and down navigation in the menu level. |
|  | O | Change into operation mode. |
| Parameterisationlevel | P | To confirm the changes made at the parameterisation level. |
|  | $\triangle \nabla$ | Adjustment of the value / the setting. |
|  | O | Change into menu level or break-off in value input. |
| Menu group level | P | Change to menu level. |
|  | $\triangle \square$ | Keys for up and down navigation in the menu group level. |
|  | 0 | Change into operation mode or back into menu level. |

## Function chart:



Underline:
(P) Takeover
(O) Stop

- Value selection (+)

Value selection (-)

### 4.1 Parameterisation software PM-TOOL:

Part of the PM-TOOL are the software on CD and the USB-cable with device adapter. The connection happens via a 4-pole micromatch-plug on the back side of the device, to the PC-side the connection happens via an USB plug.

System requirements: PC incl. USB interface
Software: Windows XP, Windows VISTA
With this tool the device configuration can be generated, omitted and saved on the PC. The parameters can be changed via the easy to handle program surface, whereat the operating mode and the possible selection options can be preset by the program.

## 5. Setting up the device

### 5.1. Switching on

Once the installation is complete, start the device by applying the voltage supply. Before, check once again that all electrical connections are correct.

## Starting sequence

For 1 second during the switching-on process, the segment test ( 8 8 8 8 8) is displayed followed by an indication of the software type and, after that, also for 1 second the software version. After the starting sequence, the device switches to operation/display mode.

### 5.2. Standard parameterisation: (Flat operation level)

To parameterise the display, press the [P] key in operating mode for 1 second. The display then changes to the menu level with the first menu item TYPE.
Menu level


| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & B_{\Delta L} \cdot \boldsymbol{R} \\ & \|\nabla \Delta\| \mid \end{aligned}$ | Selection of analog output，OUT．RR： <br> Default：4－20 <br> Three output signals are available：0－10 VDC，0－20 mA and 4－20 mA，with this function，the demanded signal is selected． |
|  | Setting up the final value of the analog output，OUT．EM： <br> Default： 10000 <br> The final value is adjusted from the smallest digit to the highest digit with［ $\mathbf{\Delta}$ ］［ $\mathbf{\nabla}$ ］and digit by digit confirmed with $[P]$ ．A minus sign can only be parameterised on the highest digit．After the last digit，the device changes back into menu level． |
|  | Setting up the initial value of the analog output，OUT．OF： <br> Default： 00000 <br> The final value is adjusted from the smallest digit to the highest digit with［ $\mathbf{\Delta}$ ］［ $\mathbf{\nabla}$ ］and digit by digit confirmed with［P］．A minus sign can only be parameterised on the highest digit．After the last digit，the device changes back into menu level． |
| $\begin{aligned} & \hline L I-I \\ & \|\nabla \Delta\| \\ & \|\nabla \Delta\| \end{aligned}$ | Threshold values／limits，LI－1： <br> Default： 2000 <br> This value defines the threshold，that activates／deactivates an alarm． |
| $\begin{aligned} & H \exists-i \\ & \|\nabla \Delta\| \end{aligned}$ | Hysteresis for limit values， HY －7： <br> Default： 00000 <br> The delayed reaction of the alarm is the difference to the threshold value，which is defined by the hysteresis． |


| Menu level | Parameterisation level |
| :---: | :---: |
|  | Function for threshold value undercut $/$ exceedance, $F U-1$ : Default: НІGH <br> A limit value undercut is selected with LOUU (for LOW = lower limit value), a limit value exceedance with $\operatorname{HIGH}$ (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function $H_{I G H}$, an alarm is activated by reaching of the threshold level. If the threshold value was allocated to LOW, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero. |
| $\begin{aligned} & \begin{array}{\|l\|l\|} \hline L & I \\ \hline \boldsymbol{I} \\ \hline \nabla & \Delta \\ \hline \end{array} \end{aligned}$ | Threshold values / limits, Ll-z: <br> Default: 2000 <br> This value defines the threshold, that activates/deactivates an alarm. |
| $\begin{aligned} & \hline H \Xi-\Sigma \mid \\ & \|\nabla \Delta\| \end{aligned}$ | Hysteresis for limit values, Hy -2: <br> Default: 00000 <br> The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis. |
| $\begin{aligned} & \square F_{\Perp}-\Xi \\ & \nabla \Delta \Delta \mid \end{aligned}$ | Function for threshold value undercut $/$ exceedance, $F U-2$ : Default: HIGH <br> A limit value undercut is selected with LOUU (for LOW = lower limit value), a limit value exceedance with HIGH (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function $H_{G H}$, an alarm is activated by reaching of the threshold level. If the threshold value was allocated to LOW, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero. |


| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \text { LILGGE } \\ & \\| \nabla \Delta \mid \end{aligned}$ | User code (4-digit number-combination, free available), U.CODE: Default: 0000 <br> If this code was set (>0000), all parameters are locked for the user, if LOC has been selected before under menu item RUM. By pressing [P] for 3 seconds in operation mode, the display shows CODE. The U.CODE needs to be entered to get to the reduced number of parameter sets. The code has to be entered befor each parameterisation, until the $\operatorname{R.CODE}$ (master code) unlocks all parameters again. |
| $\begin{aligned} & \text { REDGE } \\ & \|\nabla \Delta\| \mid \end{aligned}$ | Master code (4-digit number-combination, free available), R.CODE: <br> Default: 1234 <br> All parameters can be unlocked with this code, after LOC has been activated under menu item RUM. By pressing [P] for 3 seconds in operation mode, the display shows CODE and enables the user to reach all parameters by entering the R.CODE. Under RUM the parameterisation can be activated permanently by selecting $U L O C$ or $P R O F$, thus at an anew pushing of $[P]$ in operation mode, the code needs not to be entered again. |
| 5.3. Programming interlock „RUM4 |  |
|  | Activation / deactivation of the programming lock or completion of the standard parameterisation with change into menu group level (complete function range), RUM: Default: ULOC <br> With the navigation keys [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ], choose between the deactivated key lock ULOC (works setting) and the activated key lock LOC, or the change into the menu group level PROF. Confirm the selection with [P]. After this, the display confirms the settings with ". . . .-" and switches automatically to operating mode. If LOC was selected, the keyboard is locked. To get back into the menu level, press [P] for 3 seconds in operating mode. Now enter the CODE (works setting 1234 ) that appears using [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ] plus [P] to unlock the keyboard. FRIL appears if the input was wrong. To parameterise further functions PROF needs to be set. The device confirms this setting with „- - -, and changes automatically into operation mode. By pressing [P] for approx. 3 seconds in operation mode, the first menu group IMP is shown in the display and thus confirms the change into the extended parameterisation. It stays activated as long as ULOC or LOC is entered in menu group RUM. |

### 5.4. Extended parameterisation (professional operation level)

### 5.4.1. Signal input parameters




| Menu level | Parameterisation level |
| :---: | :---: |
|  | Setting up the display time, $5 E C$ : <br> Default: 1.0 <br> DTI! $\square$ 04.9 then <br> $\square$ I. 1 $\square$ <br> The display time is set with [ $\mathbf{A}$ ] [ $\mathbf{\nabla}$ ]. The display moves up in increments of 0.1 up to 1 second and in increments of 1.0 up to 10.0 seconds. Confirm the selection by pressing the [P] button. The display then switches back to the menu level again. |
|  | Rescaling the measuring input values, EMDA: <br> Default: 10000 <br> With this function, you can rescale the input value of e.g. 19.5 mA (works setting) without applying a measuring signal. If sensor calibration has been selected, these parameters are not available. |
| $\begin{aligned} & \boxed{A F F 5 R} \\ & \|\nabla \Delta\| \end{aligned}$ | Rescaling the measuring input values, OFFR: <br> Default: 0 <br> With this function, you can rescale the input value of e.g. $\mathbf{3 . 5} \mathrm{mA}$ (works setting) without applying a measuring signal. If sensor calibration has been selected, these parameters are not available. |
| $\begin{aligned} & \|L R\|-R \\ & \|\nabla \Delta\| \end{aligned}$ | Setting up the tare/offset value, TRRR: <br> Default: 0 $\square$ $\square$ $\square$ $\square$ <br> The given value is added to the linearised value. In this way, the characteristic line can be shifted by the selected amount. |
|  | Setting up the balance point, RDJ.PT: <br> Default: 08000 <br> The balance point for the final value can be chosen from the measuring range by SENS.U with $0 \ldots 10 \mathrm{~V}$ or 5 EMS.. with $0 . . .20 \mathrm{~mA}$ in $\%$. The preset $80.000 \%$ result from the widespread detuning of the melt pressure sensors. |
|  | Number of additional setpoints, SPCT: <br> Default: 00 <br> 30 additional setpoints can be defined to the initial- and final value, so linear sensor values are not linearised. Only activated setpoint parameters are displayed. |


| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{array}{ll} \square i & 5.7 \\ \mid \nabla & \Delta \end{array}$ | Display values for setpoints， 1015.01 ．．．D15．30： <br> Under this parameter setpoints are defined according to their value．At the sensor calibration， like at final value／offset，one is asked at the end if a calibration shall be activated． |
| $\begin{aligned} & \therefore \cap \square . \square i \\ & \|\nabla \Delta \Delta\| \end{aligned}$ | Analog values for setpoints，IMP． 01 ．．．IMP． 30 ： <br> The setpoints are always set according to the selected input signal．The desired analog values can be freely parameterised in ascending order． |
|  | Device undercut，DIIUMD： <br> Default：－19999 <br> With this function the device undercut（ $\qquad$ ＿）can be defined on a definite value．Exception is input type 4－20 mA，it already shows undercut at a signal $<1 \mathrm{~mA}$ ，so a sensor failure is marked． |
|  | Display overflow，DI．OUE： <br> Default： 99999 |
|  | Input variable of process value，SIG．IM： <br> Default：R．MERS <br> RTHERS <br> Rbu5 $\square$ <br> With this parameter，the device can be controlled via the analog input signals R．MERS $=0-20 \mathrm{~mA}$ ， 4－20 mA or 0－10 VDC or via the digital signals of the interface m．BUS＝RS232／RS485（Modbus protocol）．With［P］the selection is confirmed and the device changes into menu level． |
| $\begin{aligned} & \square-E L \\ & \|\nabla \Delta\| \end{aligned}$ | Back to menu group level，RET： <br> With［P］the selection is confirmed and the device changes into menu group level ．．－IMP－＂． |

### 5.4.2. General device parameters



(

| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \begin{array}{\|l\|l\|} \hline L & L \end{array} \\ & \|\nabla \Delta \Delta\| \end{aligned}$ | Brightness control, LIGHT: <br> Default: 10 <br> The brightness of the display can be adjusted in 16 levels from $00=$ very dark to $15=$ very bright via this parameter or alternatively via the navigation keys from the outside. During the start of the device, the level that is deposited under this parameter will always be used, even though the brightness has been changed via the navigation keys in the meantime. |
| $\begin{aligned} & \text { FLGGH } \\ & \nabla \triangle \Delta \mid \end{aligned}$ | Display flashing, FLRSH: <br> Default: MO <br> A display flashing can be added as additional alarm function either to single or to a combination of off-limit condition. With MO, no flashing is allocated. |
| $\begin{aligned} & \text { LロL! } \\ & \nabla \Delta \Delta \mid \end{aligned}$ | Assignment (deposit) of key functions, TRST: <br> Default: MO <br> For the operation mode, special functions can be deposited on the navigation keys [ $\mathbf{A}$ ] [ $\mathbf{V}$ ] , in particular this function is made for devices in housing size $48 \times 24 \mathrm{~mm}$ which do not have a 4th key ([O]-key). If the min/max-memory was activated by EHTR, all measured min/max-values are saved during operation and can be recalled via the navigation keys. The values get lost by restart of the device. If the threshold value correction $L I .12$ or $L 1.34$ was choosen, the values of the threshold can be changed during operation without disturbing the operating procedure. With TRRR the device is tared to zero and saved permanently as offset. The device confirms the correct taring by showing 00000 in the display SET.TR switches into the offset value and can be changed via the navigation keys [ $\mathbf{A}$ ] [ $\mathbf{\nabla}$ ]. Via TOTRL the current value of the totaliser can be displayed for approx. 7 seconds, after this the device changes back on the parameterised display value. If TOT.RE is deposited, the totaliser can be set back by pressing of the navigation keys [ $\mathbf{\Delta}$ ] [ $\mathbf{\nabla}$ ], the device acknowledges this with 00000 in the display. The configuration of EHT.RE deletes the min/max-memory. Under RCTUR the measurand is shown for approx. 7 seconds, after this the display returns to the parameterised display value. If RBS.UR (absolute value) was selected, the display shows the value that has been measured since voltage connection, without consideration of a previous taring. If $M O$ is selected, the navigation keys are without any function in the operation mode. |


| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \text { LREL. } \\ & \nabla \nabla \Delta \mid \end{aligned}$ | Special function [O]-key, TRST.4: <br> Default: MO <br> For the operation mode, special functions can be deposited on the [0]-key. This function is activated by pressing the key. With TRRR the device is set temporarily on a parameterised value. The device acknowledges the correct taring with 00000 in the display. SET.TR switches into the offset value and can be changed via the navigation keys [ $\mathbf{\Delta}$ ] [ $\mathbf{\nabla}$ ]. Via TOTRL the current value of the totaliser can be displayed for approx. 7 seconds, after this the device switches back on the parameterised display value. If TOT.RE was deposited, the totaliser can be set back by pressing of the navigation keys [4] [7], the device acknowledges this with showing 00000 in the display. EHT.RE deletes the min/max-memory. If $H O L D$ has been selected, the moment can be hold constant by pressing the [O]-key and is updated by releasing the key. Advice: HOLD is activated only, if HOLD was selected under parameter DISPL. RCTUR shows the measuring value for approx. 7 seconds, after this the device switches back on the parameterised display value. The same goes for $\mathbb{R V G}$, here the sliding average values will be displayed. A sensor calibration is done by triggering of the digital input via SE.CRL, the flow diagram is shown in Chapter 9. The constant value cONST can be recalled via the digital input, or changed digit per digit. At RL-1...RL-4 an output can be set and therewith e.g. a setpoint adjustment can be done. If MO is selected, the [O]-key is without any function in the operation mode. |
|  | Special function digital input, DIG.IM: <br> Default: MO <br> In operation mode, the above shown parameters can be laid on the optional digital input, too. Function description see TRST.4. |
| $\begin{aligned} & \mid r E L \\ & \|\nabla \Delta\| \end{aligned}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level ..-FCT-". |

### 5.4.3. Bargraph functions



| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \operatorname{GB} 5 r \\ & \|\nabla \Delta\| \end{aligned}$ | Bargraph, BR.5RC: <br> Default: RCTUR <br> With this function the following values can be allocated to the display: the current measuring value, min/max value, totaliser value or the process-controlled hold value, the sliding average value, the constant value or the difference between constant value and current value of the display. With [P] the selection is confirmed and the device changes into menu level. |
|  | Setting up the final value of the bargraph, BR.EMD: <br> Default: 10000 <br> Set the final value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ] [ $\mathbf{\nabla}$ ] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level. |
| $\begin{aligned} & \square R M F F \\ & \nabla \triangle \Delta \end{aligned}$ | Setting up the initial value of the bargraph, BR.OFF: <br> Default: 0 <br> Set the initial value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ] [ $\mathbf{\nabla}$ ] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level. |
| $\begin{aligned} & \square F G L L \\ & \nabla \triangle \Delta \end{aligned}$ | Selection of the bargraph functions, BA.FCT: <br> Default: BRR.FO <br> The bargraph can be displayed with the following possibilities: bars forwards, bars backwards, bars starting out of the middle, bars from the middle, a dot display of the bargraph or a dot display with a permanently displayed midpoint. Confirm the selection by pressing the [P] button. The display then switches back to the menu level again. |

Menu level

### 5.4.4. Safety parameters



| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \text { HiLa』E } \\ & \|\nabla \Delta\| \end{aligned}$ | Setting up the user code, U.CODE: <br> Default: 0000 <br> Via this code, reduced sets of parameters OUT.LE and RL.LEV can be unlocked, in case of a locked programming. There is no access to further parameters via this code. The U.CODE can only be changed via the correct input of the $\operatorname{R.CODE}$ (master code). |
| $\begin{aligned} & \text { RLGUE } \\ & \|\nabla \Delta\| \mid \end{aligned}$ | Master code, f.CODE: <br> Default: 1234 <br> By entering R.CODE the device will be unlocked and all parameters are released. |
| $\begin{aligned} & \text { BLELE } \\ & \uparrow \nabla \Delta \mid \end{aligned}$ | Release/lock analog output parameter, oUT.LE: Default: RLL $\square$ $1 \square$ <br> En-DF <br> DuE.ED <br> RLL <br> Analog output parameter can be locked or released for the user: <br> - EM-OF: the initial or final value can be changed in operation mode <br> - OUT.EO: the output signal can be changed from e.g. 0-20 mA to 4-20 mA or 0-10 VDC <br> - RLL: analog output parameters are released <br> - MO: all analog output parameters are locked |
| RLLEL | Release/lock alarm parameters, RL.LEU: <br> Default: RLL <br> This parameter describes the user release/user lock of the alarm: <br> - LIMIT: here only the range of value of the threshold values 1-4 can be changed <br> - RLRM.L: here the range of value and the alarm trigger can be changed <br> - RLL: all alarm parameters are released <br> - MO: all alarm parameters are locked |


| Menu level |  | Parameterisation level |
| :--- | :--- | :--- |
|  | $I$ | $\Sigma$ |

### 5.4.5. Serial parameters


Menu level

### 5.4.6. Analog output parameters



| Menu level | Parameterisation level |
| :--- | :--- | :--- |
| Selection reference of analog output, outpt: |  |
| Defaut: actur |  |


| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \square . F L D H \\ & \|\nabla \Delta\| \end{aligned}$ | Overflow behaviour, O.FLOU: <br> Default: EDGE <br> EdらE <br> Ea.End <br> ED.DFF <br> Ea.Mil $n$ <br> Ea.MRH $\square$ <br> To recognise and evaluate faulty signals, e.g. by a controller, the overflow behaviour of the analog output can be defined. As overflow can be seen either $\operatorname{EDGE}$, that means the analog output runs on the set limits e.g. 4 and 20 mA , or $\operatorname{T0.0FF}$ (input value smaller than initial value, analog output switches on e.g. 4 mA ), TO.END (higher than final value, analog output switches on e.g. 20 mA ). If TO.MIM or TO.MRX is set, the analog output switches on the smallest or highest possible binary value. This means that values of e.g. $0 \mathrm{~mA}, 0 \mathrm{VDC}$ or values higher than 20 mA or 10 VDC can be reached. With [P] the selection is confirmed and the device changes into menu level. |
| $\begin{aligned} & \mid r E L \\ & \|\nabla \Delta\| \end{aligned}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level ..-OUT-". |

### 5.4.7. Relay functions






### 5.4.8. Alarm parameters


Menu level

| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{array}{l\|l\|l\|} \hline L & I & - \\ \hline \nabla & \Delta \end{array}$ | Threshold values / limit values, $\mathrm{LL}-\mathrm{T}$ : <br> Default: 2000 <br> The limit value defines the threshold, that activates/deactivates an alarm. |
| $\begin{aligned} & \square H- \\ & \nabla \nabla \Delta \mid \end{aligned}$ | Hysteresis for threshold values, $\mathrm{HY}-\mathrm{l}$ : <br> Default: 00000 $\square$ $\square$ $\square$ <br> The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis. |
| $\begin{aligned} & \mid F_{\Delta}- \\ & \|\nabla \Delta\| \end{aligned}$ | Function for threshold value undercut / exceedance, FU-1: Default: HIGH <br> A limit value undercut is selected with LOUU (for LOW = lower limit value), a limit value exceedance with HIGH (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function $H$ HGH, an alarm is activated by reaching the threshold level. If the threshold value was allocated to LOW, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero. |
| $\begin{array}{c\|} \text { Lロח- } \\ \|\nabla \Delta\| \end{array}$ | Switching-on delay, TOM-7: <br> Default: 000 <br> For limit value 1 one can preset a delayed switching-on of 0-100 seconds. |
| $\begin{aligned} & \text { LaF-i } \\ & \nabla \Delta \Delta \mid \end{aligned}$ | Switching-off delay, TOF-l: <br> Default: 000 $\square$ $\square$ <br> For limit value 1 one can preset a delayed switching-off of 0-100 seconds. |
| $\begin{aligned} & \square \\ & \hline-E L \\ & \nabla \Delta \mid \end{aligned}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level ..-RLI-". |

The same applies for RL2 to RL8.

### 5.4.9. Totaliser (Volume metering)



| Menu level | Parameterisation level |
| :--- | :--- | :--- |
| Totaliser state, TOTRL: |  |
| Default: off |  |


| Menu level | Parameterisation level |
| :--- | :--- | :--- |

## Programming interlock, RUN:



Description see page 11, menu level RUM

## 6. Reset to default values

To return the unit to a defined basic state, a reset can be carried out to the default values.
The following procedure should be used:

- Switch off the power supply
- Press button [P]
- Switch on voltage supply and press [P]-button until ......" is shown in the display.

With reset, the default values of the program table are loaded and used for subsequent operation.
This puts the unit back to the state in which it was supplied.

## Caution! All application-related data are lost.

## 7. Alarms / Relays

This device has 4 virtual alarms that can monitor one limit value in regard of an undercut or exceedance. Each alarm can be allocated to an optional relay output S1-S2; furthermore alarms can be controlled by events like e.g. hold-value or min/max-value.

Function principle of alarms / relays

| Alarm / Relay $\mathbf{x}$ | Deactivated, instantaneous value, min/max-value, hold-value, <br> totaliser value, sliding average value, constant value, difference <br> between instantaneous value and constant value or an activation <br> via the digital input |
| :--- | :--- |
| Switching threshold | Threshold / limit value of the change-over |
| Hysteresis | Broadness of the window between the switching thresholds |
| Working principle | Operating current / Quiescent current |



## Operating current

By operating current the alarm S1-S2 is off below the threshold and on on reaching the threshold.

## Quiescent current

By quiescent current the alarm S1-S2 is on below the threshold and switched off on reaching the threshold.

## Switching-on delay

The switching-on delay is activated via an alarm and e.g. switched 10 seconds after reaching the switching threshold, a shortterm exceedance of the switching value does not cause an alarm, respectively does not cause a switching operation of the relay. The switching-off delay operates in the same way, keeps the alarm / the relay switched longer for the parameterised time.

## 8. Interfaces

## Connection RS232

Digital device M3 PC-9-pole Sub-D-plug


## Connection RS485

Digital device M3


The interface RS485 is connected via a screened data line with twisted wires (Twisted-Pair). On each end of the bus segment a termination of the bus lines needs to be connected. This is neccessary to ensure a secure data transfer to the bus. For this a resistance ( 120 Ohm ) is interposed between the lines Data B (+) and Data A ( - ).

## 9. Sensor alignment offset / final value

The device is equipped with a semi-automatic sensor calibration (SEMSU/SEMSR). A switching output operates the trimming resistor, which exists in some sensors. An adjustment of offset and final value takes place, after which the sensor can be used directly. Depending on parameterisation, the calibration can be realized via the 4th key or via the digital input. It is possible to key during the calibration steps. So, reference signals can be connected manually. However, the calibration will be interrupted after 30 seconds.


## 10. Technical data

| Panel meter |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Dimensions | 96x96x56 mm (BxHxD) |  |  |  |
|  | 96x96x82 mm (BxHxD) including plug-in terminal |  |  |  |
| Panel cut-out | $91.0^{+0.6} \times 91.0^{+0.6} \mathrm{~mm}$ |  |  |  |
| Wall thickness | up to 10 mm |  |  |  |
| Fixing | screw elements |  |  |  |
| Material | LEXAN 500R, black |  |  |  |
| Sealing material | EPDM, 65 Shore, black |  |  |  |
| Protection class | standard IP65 (front), IP00 (back side) |  |  |  |
| Weight | approx. 330 g |  |  |  |
| Connection | plug-in terminal; wire cross section up to $2.5 \mathrm{~mm}^{2}$ |  |  |  |
| Display |  |  |  |  |
| Digit height | 14 mm |  |  |  |
| Segment colour | red |  |  |  |
| Display range | -19999 to 99999 |  |  |  |
| Setpoints | one LED per setpoint |  |  |  |
| Overflow | horizontal bars at the top |  |  |  |
| Underflow | horizontal bars at the bottom |  |  |  |
| Display time | 0.1 to 10.0 seconds |  |  |  |
| Bargraph | 55 segments in a $270^{\circ}$ angle |  |  |  |
| Bragraph colour | red |  |  |  |
| Input | Measuring range | Ri | Measuring error | Digit |
| min. -22...max. 24 mA | 0/4-20 mA | $\sim 100 \Omega$ | 0.1 \% of measuring range | $\pm 1$ |
| min. -12...max. 12 VDC | 0-10 VDC | $\sim 200 \mathrm{k} \Omega$ | 0.1 \% of measuring range | $\pm 1$ |
| Digital input | $\begin{aligned} & <2,4 \mathrm{~V} \text { OFF, } 10 \mathrm{~V} \text { ON, max. } 30 \mathrm{VDC} \\ & \mathrm{R}_{1} \sim 5 \mathrm{k} \Omega \end{aligned}$ |  |  |  |
| Accuracy |  |  |  |  |
| Drift of temperature | $100 \mathrm{ppm} / \mathrm{K}$ |  |  |  |
| Measuring time | 0.1...10.0 seconds |  |  |  |
| Measuring principle | U/F-conversion |  |  |  |
| Resolution | approx. 18 bit at 1 second measuring time |  |  |  |


| Output |  |
| :---: | :---: |
| Sensor supply | $24 \mathrm{VDC} / 50 \mathrm{~mA}$; $12 \mathrm{VDC} / 50 \mathrm{~mA}$; $5 \mathrm{VDC} / 20 \mathrm{~mA}$ |
| Analog output | 0/4-20 mA /burden $350 \Omega$ or 0-10 VDC / $10 \mathrm{kOhm}, 16$ bit |
| Switching outputs |  |
| Relay with change-over contacts Switching cycles | 250 VAC / 5 AAC; 30 VDC / 5 ADC <br> $30 \times 10^{3}$ at 5 AAC, 5 ADC ohm resitive burden <br> $10 \times 10^{6}$ mechanically <br> Division according to DIN EN50178 / <br> Characteristics accrording to DIN EN60255 |
| Interface |  |
| Protocol | Modbus with ASCII or RTU-protocol |
| RS232 | 9.600 Baud, no parity, 8 Databit, 1 Stopbit, wire length max. 3 m |
| RS485 | 9.600 Baud, no parity, 8 Databit, 1 Stopbit, wire length max. 1000 m |
| Power supply | $100-240$ VAC $50 / 60 \mathrm{~Hz}, \mathrm{DC} \pm 10 \%$, max. 15 VA 10-40 VDC; 18-30 VAC $50 / 60 \mathrm{~Hz}$, max. 15 VA |
| Memory | EEPROM |
| Data life | $\geq 100$ years at $25^{\circ} \mathrm{C}$ |
| Ambient conditions |  |
| Working temperature | $0^{\circ} \ldots 50^{\circ} \mathrm{C}$ for panel meters, $-20^{\circ} \ldots 60^{\circ} \mathrm{C}$ for built-on devices |
| Storing temperature | $-20 . .80^{\circ} \mathrm{C}$ |
| Weathering resistance | relative humidity 0-80\% on years average without dew |
| Height | up to 2000 m above sea level |
| EMV | EN 61326 |
| CE-sign | Conformity according to directive 2004/108/EG |
| Safety standard | Accroding to low voltage directive 2006/95/EG EN 61010; EN 60664-1 |

## 11. Safety advices

Please read the following safety advices and the assembly chapter 1 before installation and keep it for future reference.

## Proper use

The IMB2-2V-device is designed for the evaluation and display of sensor signals.


## Danger! Careless use or improper operation can result in

 personal injury and/or cause damage to the equipment.
## Control of the device

The panel meters are checked before dispatch and sent out in perfect condition. Should there be any visible damage, we recommend close examination of the packaging. Please inform the supplier immediately of any damage.

## Installation

The IMB2-2V-device must be installed by a suitably qualified specialist (e.g. with a qualification in industrial electronics).

## Notes on installation

- There must be no magnetic or electric fields in the vicinity of the device, e.g. due to transformers, mobile phones or electrostatic discharge.
- The fuse rating of the supply voltage should not exceed a value of 0.5A N.B. fuse!
- Do not install inductive consumers (relays, solenoid valves etc.) near the device and suppress any interference with the aid of RC spark extinguishing combinations or free-wheeling diodes.
- Keep input, output and supply lines separate from one another and do not lay them parallel with each other. Position "go" and "return lines" next to one another. Where possible use twisted pair. So, you receive best measuring results.
- Screen off and twist sensor lines. Do not lay current-carrying lines in the vicinity. Connect the screening on one side on a suitable potential equaliser (normally signal ground).
- The device is not suitable for installation in areas where there is a risk of explosion.
- Any electrical connection deviating from the connection diagram can endanger human life and/or can destroy the equipment.
- The terminal area of the devices is part of the service. Here electrostatic discharge needs to be avoided. Attention! High voltages can cause dangerous body currents.
- Galvanic isolated potentials within one complex need to be placed on a appropriate point (normally earth or machines ground). So, a lower disturbance sensibility against impacted energy can be reached and dangerous potentials, that can occur on long lines or due to faulty wiring, can be avoided.


## 12. Error elimination

|  | Error description | Measures |
| :--- | :--- | :--- |
| 1. | The unit permanently indicates <br> overflow. <br> • The input has a very high measurement, check <br> the measuring circuit. <br> - With a selected input with a low voltage signal, it <br> is only connected on one side or the input is open. <br> - Not all of the activated setpoints are <br> parameterised. Check if the relevant parameters <br> are adjusted correctly. |  |
| 2. | The unit permanently shows <br> underflow. | - The input has a very low measurement, check the <br> measuring circuit. |
| - With a selected input with a low voltage signal, it |  |  |
| is only connected on one side or the input is open. |  |  |
| - Not all of the activated setpoints are |  |  |
| parameterised. Check if the relevant parameters |  |  |
| are adjusted correctly. |  |  |$|$| • The unit has found an error in the configuration |
| :--- |
| memory. Perform a reset on the default values |
| and reconfigure the unit according to your |
| application. |

