## User manual IMB3-3V

## Direct current / direct voltage signals $\mathbf{0 - 2 0} \mathrm{mA}, 4-20 \mathrm{~mA}, 0-10$ VDC


-3-digit red display of -199... 999 digits (optional green)

- 20 points bargraph tricolour (red/orange/green)
- adjustable bar or dot operation or operation with permanent display of center point
- min/max memory
- 30 additional adjustable setpoints
- display flashing at threshold value exceedance/undercut
- zero-key for triggering of Hold, Tara
- permanent min/max-value recording
- volume metering (totalisator)
- mathematical functions like reciprocal value, square root, squaring or rounding
- sliding averaging
- programming interlock via access code
- protection class IP65 at the front
- plug-in screw terminal
- optional: 1 or 2 relay outputs (changer)
- optional: sensor supply
- optional: galv. isolated digital input for triggering of Tara, Hold, display change
- optional: 1 independently scalable analog output
- optional: interface RS232 or RS485
- accessories: PC-based configuration kit PM-TOOL with CD and USB-adaptor for devices without keypad and for a simple adjustment of standard devices


## Identification

| STANDARD-TYPES | ORDER NUMBERS |
| :--- | :---: |
| Direct current / direct voltage <br> Housing size: $96 \times 24 \mathrm{~mm}$ | IMB3-3VT3xR.0001.S70xD <br> IMB3-3VT3xR.0001.W70xD |

Options - break-down ordering code:


Please state physical unit by order, e.g. \%.

## Contents

1. Brief description ..... 2
2. Assembly ..... 2
3. Electrical connection ..... 3
4. Description of function and operation ..... 6
4.1. Programming software PM-TOOL ..... 7
5. Setting up the device ..... 8
5.1. Switching on ..... 8
5.2. Standard parameterisation (flat operation level) ..... 8Value assignment for the triggering of the signal input of the digital display and bargraph display
5.3. Programming interlock .RUM" ..... 11
Activiation/Deactivation of the programming interlock or change into professional operation level respectively back into flat operation level
5.4. Extended parameterisation (professional operation level) ..... 12
5.4.1. Signal input parameters „IMP" ..... 12
Value assignment for the triggering of the signal input incl. linearisation of the digital display and the bargraph display
5.4.2. General device parameters „FCT" ..... 15
Superior device functions like Hold, Tara, min/max permanent, averaging, as well as the control of the digital input and keyboard layout
5.4.3. Bargraph functions „BRR" ..... 18
Assignment of the bargraph to superior functions like min/max, totaliser, Hold or sliding averaging
5.4.4. Safety parameters „COD" ..... 20
Assignment of user and master code for locking respectively for access to defined parameters like e.g. analog output and alarms, etc.
5.4.5. Serial parameters „SER" ..... 21
Parameters for the definition of the interface
5.4.6. Analog output parameters „OUT، ..... 22
Analog output functions
5.4.7. Relay functions „REL" ..... 24
Parameters for the definition of the setpoints
5.4.8. Alarm parameters „RLI...RL4" ..... 25
Actuator and dependencies of the alarms
5.4.9. Totaliser (volume metering) „TOT" ..... 27
Parameters for the calculation of the sum function
6. Reset to factory settings ..... 28Reset parameters to delivery state
7. Alarms / Relay ..... 29
Functional principle of the switching outputs
8. Interfaces ..... 30
Connection RS232 and RS485
9. Technical data ..... 31
10. Safety advices ..... 33
11. Error elimination ..... 34

## 1. Brief description

The panel meter instrument IMB3-3V is a 3-digit digital display with a 30 points bargraph display and optional two galvanic isolated setpoints; designed for direct current/direct voltage signals. The configuration happens via 4 keys at the front. The integrated programming interlock prevents unrequested changes of parameters and can be unlocked again with an individual code. Optional the following functions are available: a supply for the sensor, a digital input for triggering of Hold (Tara), two analog outputs and interfaces for further evaluating in the unit. The electrical connection is done via plug-in terminals on the back side.
Selectable functions like e.g. the recall of the min/max-value, an averaging of the measuring signals, a direct threshold value regulation during operation mode and further measuring setpoints for linearisation, complete the modern device concept.

## 2. Assembly

Please read the Safety advices on page 33 before installation and keep this user manual for future reference.


1. After removing the fixing elements, insert the device.
2. Check the seal to make sure it fits securely.
3. Click the fixing elements back into place and tighten the clamping screws by hand. Then use a screwdriver to tighten them another half a turn.

CAUTION! The torque should not exceed 0.1 Nm !

The dimension symbols can be exchanged before installation via a channel on the side!
(This is only true for the horizontal design. For the vertical design, this needs to be quoted with the order!)

## 3. Electrical connection

Type IMB3-3VT3HR.0001.S70xD supply of 100-240 VAC $50 / 60 \mathrm{~Hz}, \mathrm{DC} \pm 10 \%$ horizontally Type IMB3-3VT3VR.0001.S70xD supply of $100-240$ VAC $50 / 60 \mathrm{~Hz}, \mathrm{DC} \pm 10 \%$ vertically

Type IMB3-3VT3HR.0001.W70xD supply of 10-30 VDC, galv. isolated, $18-30$ VAC $50 / 60 \mathrm{~Hz}$ horizontally Type IMB3-3VT3VR.0001.W70xD supply of 10-30 VDC, galv. isolated, 18-30 VAC 50/60 Hz vertically


Options:

or


Alternative to analog output

S2


Relay 2

S1


Relay 1

IMB3 with digital input in combination with a 24 VDC sensor supply

IMB3 with digital input and external voltage source


## Connection examples

Below please find some connection examples that show practical applications. For devices with current inputs / voltage inputs, without sensor supply.

MB3 in combination with a
2-wire-sensor 4-20 mA


MB3 in combination with a
3-wire-sensor 0/4-20 mA


MB3 in combination with a
3-wire-sensor 0-10 V


## IMB3 devices

With current respectively voltage input in combination with a 24 VDC sensor supply.

## 2-wire-sensor 4-20 mA



## 3-wire-sensor 0-20 mA



3-wire-sensor 0-10 V


## 4. Description of function and operation

## Operation

The operation is divided into three different levels.
Menu level (delivery status)
This level was designed for the standard settings of the device. Only menu items which are sufficent to set the device into operation are displayed. To get into the professional level, run through the menu level and parameterise PRF under menu item RUM.

Menu group level (complete function volume)
Suited for complex applications as e.g. linkage of alarms, supporting point treatment, totaliser function etc. In this level function groups which allow an extended parameterisation of the standard settings are availabe. To leave the menu group level, run through this level and parameterise ULC under menu item RUM.

## Parameterisation level:

Parameter deposited in the menu item can here be parameterised. Functions, that can be changed or adjusted, are always signalised by a flashing of the display. Settings that are made in the parameterisation level are confirmed with [P] and thus saved. Pressing the [O]-key leads to a break-off of the value input and to a change into the menu level. All adjustments are saved automatically by the device and changes into operating mode, if no further key operation is done within the next 10 seconds.

| Level | Key | Description |
| :---: | :---: | :---: |
| Menu-level | P | Change to parameterisation level and deposited values. |
|  | $\triangle \nabla$ | Keys for up and down navigation in the menu level. |
|  | 0 | Change into operation mode. |
| Parameterisationlevel | P | To confirm the changes made at the parameterisation level. |
|  |  | Adjustment of the value / the setting. |
|  | O | Change into menu level or break-off in value input. |
| Menu group level | P | Change to menu level. |
|  | $\triangle \square$ | Keys for up and down navigation in the menu group level. |
|  | 0 | Change into operation mode or back into menu level. |

## Function chart:



## Underline:



### 4.1 Parameterisation software PM-TOOL:

Part of the PM-TOOL are the software on CD and the USB-cable with device adapter. The connection happens via a 4-pole micromatch-plug on the back side of the device, to the PC-side the connection happens via an USB plug.

System requirements: PC incl. USB interface
Software: Windows XP, Windows VISTA
With this tool the device configuration can be generated, omitted and saved on the PC. The parameters can be changed via the easy to handle program surface, whereat the operating mode and the possible selection options can be preset by the program.

## CAUTION!

During parameterisation with connected measuring signal, make sure that the measuring signal has no mass supply to the programming plug. The programming adapter is galvanic not isolated and directly connected with the PC. Via polarity of the input signal, a current can discharge via the adapter and destroy the device as well as other connected components!

## 5. Setting up the device

### 5.1. Switching on

Once the installation is complete, start the device by applying the voltage supply. Before, check once again that all electrical connections are correct.

## Starting sequence

For 1 second during the switching-on process, the segment test ( 888 ) is displayed followed by an indication of the software type and, after that, also for 1 second the software version. After the starting sequence, the device switches to operation/display mode.

### 5.2. Standard parameterisation: (Flat operation level)

To parameterise the display, press the [P]-key in operating mode for 1 second. The display then changes to the menu level with the first menu item TYPE.

| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{array}{r} \boxed{\boxed{L}} \boldsymbol{\square} \\ \nabla \triangle \Delta \end{array}$ | Selection of the input signal, TYP: <br> Default: SE.U D. IG <br> Available as measuring input options are $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}$ or $0-10$ VDC signals as works calibration (without application of the sensor signal) and SE.U (voltage) or SE.R (current) as sensor calibration (with the sensor applied). Confirm the selection with $[P]$ and the display switches back to menu level. |

Setting the end value of the measuring range, END:
Default: 100


Set the end value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ][ $\mathbf{\nabla}$ ] and confirm each digit with [P]. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level. If $5 E . U$ or $5 E . R$ were selected as input option, you can only select between MOC and CRL. With MOC, only the previously set display value is taken over, and with CAL, the device takes over both the display value and the analogue input value.

Setting the start/offset value of the measuring range, OFF:
Default: 0


Enter the start/offset value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ] and confirm each digit with [P]. After the last digit the display switches back to the menu level. If SEM was selected as input option, you can only select between NOC and CAL. With MOC, only the previously set display value is taken over, and with CRL, the device takes over both the display value and the analogue input value.

Setting the decimal point, $D O T$ :
Default: 0


The decimal point on the display can be moved with [ $\mathbf{\Delta}$ ] [ $\mathbf{\nabla}$ ] and confirmed with [ P ]. The display then switches back to the menu level again.

| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{gathered} \boxed{5 E} \\ \nabla \boxed{\triangle E} \end{gathered}$ | Setting up the display time, $5 E C$ : <br> Default: 1.0 <br> BI. 1 <br> DUS <br> then <br> $\square 1$. <br> B. <br> P <br> The display time is set with [ $\mathbf{A}$ ][ $\mathbf{V}$ ]. The display moves up in increments of 0.1 up to 1 second and in increments of 1.0 up to 10.0 seconds. Confirm the selection by pressing the [P] button. The display then switches back to the menu level again. |
| $\begin{gathered} \boxed{\square I I I} \\ \nabla \boxed{\nabla} \end{gathered}$ | Setting up the final value of the bargraph, B.EM: <br> Default: 100 <br> Set the final value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ][ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level. |
| $\begin{gathered} \square . \square F \\ \nabla \square \square \end{gathered}$ | Setting up the initial value of the bargraph, B.OF: <br> Default: 0 <br> Set the initial value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ][ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level. |
| $\begin{aligned} & \square . F L \\ & \nabla \triangle \end{aligned}$ | Selection of the bargraph functions, B.FC: <br> Default: BR.F $\text { bR.F } \frac{\Delta}{\nabla} \text { bR.r } \frac{\Delta}{\nabla} \text { bR. } n \frac{\Delta}{\nabla} \text { dat } \frac{\Delta}{\nabla} \text { da. } n \stackrel{\Delta}{\nabla} \mathrm{P}$ <br> The bargraph can be displayed with the following possibilites: bars from left to right (top to bottom) or bars from right to left (bottom to top), bars from the middle, a dot display of the bargraph or a dot display with a permanently displayed midpoint. Confirm the selection by pressing the $[P]$ button. The display then switches back to the menu level again. |
| $\begin{gathered} \square . E \square \\ \nabla \square \end{gathered}$ | Set the standard colour of the bargraph, B.CO: <br> Default: GRE $\square r E \sqrt{\Delta} \operatorname{arR} \sqrt{\Delta} r E d \stackrel{\Delta}{\nabla} \mathbb{P}$ <br> Under this menu item the standard colour of the display can be parameterised. The colours green, orange and red are available. Confirm the selection by pressing the [P] button. The display then switches back to the menu level again. |



## Setting up the final value of the analog output, O.EM:

Default: 100


Set the final value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ][ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level.

Setting up the initial value of the analog output, 0.0F:
Default: 0


Set the initial value from the smallest to the highest digit with [ $\mathbf{A}$ ][V] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level.
Threshold value / limit value, LI.:
Default: 20


The threshold value shows the limit, that leads to an activation of the alarm, respectively shows until which value the alarm stays inactive.
Hysteresis for threshold values, HY .1 :
Default: 0


The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis.

Function for threshold value undercut / exceedance, FU.1:
Default: HIG


A limit value undercut is selected with LOU (for LOW = lower limit value), a limit value exceedance with HIG (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function $H \mathbb{G}$, an alarm is activated by reaching of the threshold level. If the threshold value was allocated to LOU, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero.

| Menu level | Parameterisation level |
| :---: | :---: |
|  | Threshold values／limits，C．Rl： <br> Default：MO <br> LrE <br> arB <br> $r E d$ <br> Here，the colour of the bargraph that displays a breaking of ALARMI．Available are green，orange and red．If $N O$ was parameterised，the standard colouor remains．Confirm the selection with［P］ and the display switches back to menu level． |
|  | The same applies to $\mathrm{LH}-7$ to $\mathrm{Ll}-\mathrm{c}$ |
| $\begin{aligned} & \boxed{11 . 亡 日 \square} \\ & \nabla \triangle \Delta \end{aligned}$ | User code（3－digit number combination，free available），U．CODE： <br> Default： 000 <br> If this code was set（＞0000），all parameters are locked for the user，if $L O C$ has been selected before under menu item RUM．By pressing［P］for 3 seconds in operation mode，the display shows $C O D$ ．The $U . C O$ needs to be entered to get to the reduced number of parameter sets．The code has to be entered befor each parameterisation，until the R．CO（Master code）unlocks all parameters again． |
| $\begin{aligned} & R . L \square \\ & \uparrow \nabla \Delta \mid \end{aligned}$ | Master code（3－digit number－combination，free available），R．CODE： <br> Default： 123 <br> All parameters can be unlocked with this code，after LOC has been activated under menu item RUM．By pressing［P］for 3 seconds in operation mode，the display shows $C O D$ and enables the user to reach all parameters by entering the R．CO．Under RUM the parameterisation can be activated permanently by selecting UL［ or PRF，thus at an anew pushing of［P］in operation mode，the code needs not to be entered again． |
| 5．3．Programming interlock „RUM＂ |  |
|  | Activation／deactivation of the programming lock or completion of the standard parameterization with change into menu group level（complete function range），RUM： Default：ULL <br> With the navigation keys［ $\mathbf{\Delta}$ ］［ $\mathbf{V}$ ］choose between the deactivated key lock ULL（works setting） and the activated key lock LOC，or the change into the menu group level PRF．Confirm the selection with［P］．After this，the display confirms the settings with＂－－－＂，and automatically switches to operating mode．If $L O C$ was selected，the keyboard is locked．To get back into the menu level，press［P］for 3 seconds in operating mode．Now enter the $\operatorname{COD}$（works setting 12 3） that appears using［ $\mathbf{\Delta}$ ］［ $\mathbf{V}$ ］plus［P］to unlock the keyboard．FAl appears if the input was wrong． To parameterize further functions PRF needs to be set．The device confirms this setting with „－－，，and changes automatically in operation mode．By pressing［P］for approx． 3 seconds in operation mode，the first menu group IMP is shown in the display and thus confirms the change into the extended parameterisation．It stays activated as long as ULC is entered in menu group RUM，which sets the display into standard parameterisation again． |

### 5.4. Extended parameterisation (professional operation level)

### 5.4.1. Signal input parameters




四 | There are several measuring input options: $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}$ or $0-10 \mathrm{VDC}$ signals are |
| :--- |
| available as works calibration (without application of the sensor signal) and SE.U (voltage) or |
| SE.R (current) as sensor calibration (with the sensor applied). Confirm the selection with [P] and |
| the display switches back to menu level. |

Setting up the final value of the measuring range, END:
Default: 100


Set the final value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level. If SE.U or SE.R were selected as input option, you can only select between MOC and CRL. With MOC, only the previously set display value is taken over, and with CRL, the matching via the measuring section is done and the device takes over the analogue input value.
Setting up the initial value of the measuring range, OFF:
Default: 0


Set the initial value from the smallest to the highest digit with [ $\mathbf{A}$ ] [ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterised on the highest value digit. After the last digit, the display switches back to the menu level. If SE.U or $\operatorname{SE.}$. were selected as input option, you can only select between MOC and CRL. With MOC, only the previously set display value is taken over, and with CRL, the matching via the measuring section is done and the device takes over the analogue input value.
Setting the decimal point, $D O T$ :
Default: 0


The decimal point on the display can be moved with [ $\mathbf{A}$ ] [ $\mathbf{V}$ ] and confirmed with [P]. The display then switches back to the menu level again.

| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{gathered} 5 E L \\ \nabla \triangle \Delta \end{gathered}$ | Setting up the measuring time, $5 E C$ : <br> Default: 1.0 <br> DTI DUS <br> then <br> $\square 1 \square$ <br> 10.3 $\square$ <br> The measuring time is set with [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ]. The display moves up in increments of 0.1 up to 1 second and in increments of 1.0 up to 10.0 seconds. Confirm the selection by pressing the [P] button. The display then switches back to the menu level again. |

Rescaling the measuring input values, EM.R:
Default: 100


With this function, you can rescale the final value to e.g. 19.5 mA input signal, without applying a measuring signal.

Rescaling the measuring input values, OF.R:
Default: 0


Win this function, you can rescale the initial value to e.g. $\mathbf{3 . 5} \mathrm{mA}$ input signal, without applying a measuring signal.

## Setting up the tare/offset value, TRR:

Default: 0


Display values for supporting points, D.O1 ... D.30:


Under this parameter supporting points are defined according to their value. At the sensor calibration, like at „Final value/offset", one is asked at the end if a calibration shall be activated.
Menu level

### 5.4.2. General device parameters


Menu level


Assignment (deposit) of key functions, 75 :
Default: MO


For the operation mode, special functions can be deposited on the navigation keys [ $\mathbf{\Delta}$ ] [ $\mathbf{\nabla}$ ], in particular this function is made for devices in housing size $48 \times 24 \mathrm{~mm}$ which do not have a 4th key ([O]-key). If the min/max-memory was activated by EHT, all measured min/max-values are saved during operation and can be recalled via the navigation keys. The values get lost by restart of the device. If the threshold value correction L. 12 or $L .34$ is choosen, the values of the threshold can be changed during operation without disturbing the operating procedure. With TRR the device is tared to zero and saved permanently as offset. The device confirms the correct taring by showing 000 in the display. S.TR switches into the offset value and can be changed via the navigation keys $[\mathbf{\Delta}][\mathbf{V}]$. With TOT the current totaliser value can be displayed, after this, the display switches back onto the parameterised display value. If T.RE was selected, the totaliser can be set back by using the navigation keys [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ], the display confirms this by showing 000 in the display. The configuration of EH.R deletes the min/max-memory. With RCT the measurand is displayed, after this the display switches back to the parameterised display value. If $M O$ is selected, the navigation keys are without any function in the operation mode.

| Menu level | Parameterisation level |
| :--- | :--- | :--- |
| Special function [O]-key, Ts.4: |  |
| Default: MO |  |

### 5.4.3. Bargraph functions



| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{gathered} \square .5 r \\ \nabla \boxed{\Delta} \end{gathered}$ | $\begin{aligned} & \text { Bargraph, B.SR: } \\ & \text { Default: } A C T \end{aligned}$ |
|  | Adjusting the final value of the bargraph, B.EM: Default: 100 |



Set the final value from the smallest to the highest digit with [ $\mathbf{A}$ ][V] and confirm each digit with [P]. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level.

Adjusting the initial value of the bargraph, B.OF:
Default: 0


Set the initial value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level.
Selection of the bargraph functions, B.FC:
Default: BA.F for horizontal RMD BA.R for vertical



A change of colour of the bargraph to green, red or orange, can be allocated to each of the 4 alarms. The allocation of the colours is done under parameters C.AI-C.RY. Under adjustment MO, there is no change of colour, with ACT one bar segment will be switched by reaching of the alarm. PER corresponds to a permant display of the allocated alarm, even if it has not been reached yet. FLS actuates a flashing of the bargraph segment at upcoming alarm. CHG changes the complete bargraph into the colour of the alarm with highest priority, whereat the priority is set to be always ascending from alarm 1-4. In RRE-mode alarm ranges can be deposited in different colours, always in consideration of the priorities. With [P] the selection is confirmed and the device changes into menu level.
Overflow behaviour, B.OU:
Default: LIM


目 | To recognis and evaluated faulty signals, e.g. via a control, the overflow behaviour of the |
| :--- |
| bargraph can be defined. LIM can be seen as overflow, the bargraph remains on the adjusted |
| min/max-value, or $F L 5$. If $F L 5$ was selected, the complete bargraph flashes in case of an |
| overflow. With [P] the selection is confirmed and the device changes into menu level. |

## Setting the standard colour of the bargraph, B.CO:

Default: GRE

Menu level

### 5.4.4. Safety parameters



Menu level | Parameterisation level |
| :--- |

| Menu level |
| :--- |
| Parameterisation level |
| Release/lock analog output parameters, $0 . L E$ : |
| Default: RLL |

### 5.4.5. Serial parameters



| Menu level | Parameterisation level |
| :--- | :--- |
|  | Device address, $A D D:$ <br> Default: 001 |
| The device address can be adjusted from the smallest to the highest digit with the navigation <br> keys [ $\mathbf{A}$ [ $\mathbf{V}]$ and confirmed digit per digit with [P]. A device address up to max. 250 is <br> available. |  |

Menu level

### 5.4.6. Analog output parameters



| Menu level | Parameterisation level |
| :--- | :--- | :--- |
| Selection reference of analog output, 0.5R: |  |
| Default: $A C T$ |  |


| Menu level | Parameterisation level |
| :--- | :--- | :--- | :--- |
| Selection analog output, $0 . R \mathrm{RA}$ |  |
| Default: 4.20 |  |

## 5．4．7．Relay functions




Each setpoint（optional）can be linked up via 4 alarms（by default）．This can either be inserted at activated alarms R． $1 / 4$ or deactivated alarms R．MT／．If LOG was selected，logical links are available in the menu level $L 0-1$ and $[0-1$ ．Access to these two menu levels is via $L O G$ ，at all other selected functions，these two parameters are overleaped．Via OM／OFF the setpoints can be activated／deactivated，in this case the output and the setpoint display are set／not set on the front of the device．With［P］the selection is confirmed and the device changes into menu level．
Logic relay 1，LOG－1
Default：$O R$



Here，the switching behaviour of the relay is defined via a logic link，the following schema describes these functions with inclusion of $R L-1$ and $R L-2$ ：

| $\square 15$ | A1 v A2 | As soon as a selected alarm is activated，the relay operates．Equates to operating current principle． |
| :---: | :---: | :---: |
| пロr | $\overline{A 1 \vee A 2}=\overline{A 1} \wedge \overline{A 2}$ | The relay operates only，if no selected alarm is active．Equates to quiescent current principle． |
| 日ー』 | A1 $\wedge$ a2 | The relay operates only，if all selected alarms are active． |
| пワロ | $\overline{A 1 \wedge A 2}=\overline{A 1} \vee \overline{A 2}$ | As soon as a selected alarm is not activated，the relay operates． |

With $[\mathrm{P}]$ the selection is confirmed and the device changes into menu level．
Alarms for relay 1， $\mathbf{c 0 . 1}$ ：
Default： $\boldsymbol{R} .1$




The allocation of the alarms to relay 1 happens via this parameter，one alarm or a group of alarms can be chosen．With $[P]$ the selection is confirmed and the device changes into menu level．

| Menu level | Parameterisation level |
| :--- | :--- |
| $-\Sigma L$ | Back to menu group level, RET: |
| $\square$ | With $[\mathrm{P}]$ the selection is confirmed and the device changes into menu group level .REL". |

### 5.4.8. Alarm parameters



| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \boxed{5} \boldsymbol{\square} \cdot \boldsymbol{i} \\ & \nabla \boxed{\Delta} \mid \end{aligned}$ | Dependency alarm 1, 5R.I: <br> Default: ACT <br> The dependency of alarm 1 can be related to special functions, in detail these are the current measuring value, the min-value, the max-value or the totaliser value/sum-value. If HLD was selected, then the alarm is hold and processed just after deactivation of HLD. DIG causes the dependency either by pressing the [ $O$ ]-key on the front of the housing or by an external signal via the digital input. With [P] the selection is confirmed and the device changes into menu level. |
| $\begin{array}{\|l\|l\|l\|} \hline \boldsymbol{L} & \mathbf{i} & \boldsymbol{i} \\ \hline \nabla & \Delta & \\ \hline \nabla & \Delta \end{array}$ | Threshold values / limit values, LI.1: <br> Default: 20 <br> The limit value defines the threshold, that activates/deactivates an alarm. |
|  | Hysteresis for threshold values, HY .1 : <br> Default: 0 <br> The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis. |


| Menu level | Parameterisation level |
| :---: | :---: |
|  | Function for threshold value undercut / exceedance, FU.1: <br> Default: HIG <br> A limit value undercut is selected with LOU (for LOW = lower limit value), a limit value exceedance with HIG (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold level of 100 and allocated with function $H / G$, an alarm is activated by reaching of the threshold level. If the threshold value was allocated to LOU, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero. |
| $\begin{array}{c\|c\|c\|} \hline \square \pi . & i \\ \nabla & \Delta \end{array}$ | Switching-on delay, oM.l: <br> Default: 0 <br> For limit value 1 one can preset a delayed switching-on of 0-100 seconds. |
| $\begin{gathered} \square F . i \\ \nabla \triangle \Delta \end{gathered}$ | Switching-off delay, DF.l: <br> Default: 0 <br> For limit value 1 one can preset a delayed switching-off of 0-100 seconds. |
| $\begin{gathered} \boxed{-E L} \\ \nabla \Delta \end{gathered}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level .,RLI". |

The same applies for RLZ to RLY.

### 5.4.9. Totaliser (Volume metering)


Menu level

Menu level | Parameterisation level |
| :--- |

Programming interlock, RUN:


Description see page 11, menu level RUM

## 6. Reset to default values

To return the unit to a defined basic state, a reset can be carried out to the default values.
The following procedure should be used:

- Switch off the power supply
- Press button [P]
- Switch on voltage supply and press [P]-button until ..-...-" is shown in the display.

With reset, the default values of the program table are loaded and used for subsequent operation. This puts the unit back to the state in which it was supplied.

## Caution! All application-related data are lost.

## 7. Alarms / Relays

This device has 4 virtual alarms that can monitor one limit value in regard of an undercut or exceedance. Each alarm can be allocated to an optional relay output S1-S2; furthermore alarms can be controlled by events like e.g. hold value or min/max-value.

| Function principle of alarms / relays |  |
| :--- | :--- |
| Alarm / Relay $\mathbf{x}$ | Deactivated, instantaneous value, min/max-value, hold-value, totaliser <br> value, sliding average value or an activation via the digital input |
| Switching threshold | Threshold / limit value of the change-over |
| Hysteresis | Broadness of the window between the switching thresholds |
| Working principle | Operating current / Quiescent current |





## Operating current

By operating current the alarm S1-S2 is off below the threshold and on on reaching the threshold.

## Quiescent current

By quiescent current the alarm $\mathrm{S} 1-\mathrm{S} 2$ is on below the threshold and switched off on reaching the threshold.

## Switching-on delay

The switching-on delay is activated via an alarm and e.g. switched 10 seconds after reaching the switching threshold, a shortterm exceedance of the switching value does not cause an alarm, respectively does not cause a switching operation of the relay. The switching-off delay operates in the same way, keeps the alarm / the relay switched longer for the parameterised time.

## 8. Interfaces

## Connection RS232

Digital meter M3 PC-9-pole Sub-D-plug


## Connection RS485

Digital meter M3


The interface RS485 is connected via a screened data line with twisted wires (Twisted-Pair). On each end of the bus segment a termination of the bus lines needs to be connected. This is neccessary to ensure a secure data transfer to the bus. For this a resistance ( 120 Ohm ) is interposed between the lines Data $\mathrm{B}(+)$ and Data A (-).

## 9. Technical data

| Housing |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Dimensions | $96 \times 24 \times 120 \mathrm{~mm}$ (BxHxD) |  |  |  |
|  | $96 \times 24 \times 145 \mathrm{~mm}$ (BxHxD) incl. plug-in terminal |  |  |  |
| Panel cut-out | $92.0^{+0.8} \times 22.0^{+0.3} \mathrm{~mm}$ |  |  |  |
| Wall thickness | to 15 mm |  |  |  |
| Fixing | screw elements |  |  |  |
| Material | PC Polycarbonate, black, UL94V-0 |  |  |  |
| Sealing material | EPDM, 65 Shore, black |  |  |  |
| Protection class | standard IP65 (front), IP00 (back) |  |  |  |
| Weight | approx. 200 g |  |  |  |
| Connection | plug-in terminal; wire cross section up to $2.5 \mathrm{~mm}^{2}$ |  |  |  |
| Display |  |  |  |  |
| Digit height | 8 mm |  |  |  |
| Segment colour - display | red (optional green) |  |  |  |
| Range of display | -199 to 999 |  |  |  |
| Bargraph display | 30 digit, tricolour |  |  |  |
| Setpoints | one LED per setpoint |  |  |  |
| Overflow | horizontal bars at the top |  |  |  |
| Underflow | horizontal bars at the bottom |  |  |  |
| Display time | 0.1 to 10.0 seconds |  |  |  |
| Input | Measuring range | Ri | Measuring error | Digit |
| min -22... max 24 mA | 0/4-20 mA | $\sim 100 \Omega$ | 0.1 \% of measuring range | $\pm 1$ |
| min -12...max 12 VDC | 0... 10 VDC | $\sim 200 \mathrm{k} \Omega$ | 0.1 \% of measuring range | $\pm 1$ |
| Digital input | $\begin{aligned} & <2.4 \mathrm{~V} \text { OFF, }>10 \mathrm{~V} \text { ON, max. } 30 \mathrm{VDC} \\ & \mathrm{R}_{\mathrm{I}} \sim 5 \mathrm{k} \Omega \end{aligned}$ |  |  |  |
| Accuracy |  |  |  |  |
| Temperature drift | $100 \mathrm{ppm} / \mathrm{K}$ |  |  |  |
| Measuring time | $0.1 . .10 .0$ seconds |  |  |  |
| Measuring principle | U/F-conversion |  |  |  |
| Resolution | approx. 18 bit at 1 seconds measuring time |  |  |  |


| Output |  |
| :---: | :---: |
| Sensor supply | $24 \mathrm{VDC} / 50 \mathrm{~mA}$; $10 \mathrm{VDC} / 50 \mathrm{~mA}$ |
| Analog output | 0/4-20 mA / burden $\leq 500 \Omega$ or 0-10 VDC / $\geq 10 \mathrm{k} \Omega 16$ bit |
| Switching outputs |  |
| Relay with change-over contact Switching cycles | $250 \mathrm{VAC} / 2 \mathrm{AAC} ; 30 \mathrm{VDC} / 2$ ADC <br> $30 \times 10^{3}$ with 2 AAC, 2 ADC ohm resistive burden <br> $10 \times 10^{6}$ mechanically <br> Division according to DIN EN50178 / <br> Characteristics according to DIN EN60255 |
| Interface |  |
| Protocol | Modbus with ASCII or RTU-protocol |
| RS232 | 9.600 Baud, no parity, 8 databit, 1 stopbit, wire length max. 3 m |
| RS485 | 9.600 Baud, no parity, 8 databit, 1 stopbit, wire length max 1000 m |
| Power supply | 100-240 VAC, $50 / 60 \mathrm{~Hz}, \mathrm{DC} \pm 10 \%$ (max. 10 VA ) <br> 10-40 VDC galvanically isolated, 18-30 VAC $50 / 60 \mathrm{~Hz}$ (max. 10 VA ) |
| Memory | EEPROM |
| Data life | $\geq 100$ years at $25^{\circ} \mathrm{C}$ |
| Ambient conditions |  |
| Working temperature | $0^{\circ} \mathrm{C} \ldots 50^{\circ} \mathrm{C}$ for panel meters, $-20^{\circ} \mathrm{C} \ldots 60^{\circ} \mathrm{C}$ for build-up devices |
| Storing temperature | $-20^{\circ} \mathrm{C} \ldots 80^{\circ} \mathrm{C}$ |
| Climativ density | relative humidity 0-80\% on years average without dew |
| Height | up to 2000 m over sea level |
| EMV | EN 61326 |
| CE-sign | Conformity to directive 2004/108/EG |
| Safety standard | According to low voltage directive 2006/95/EG EN 61010; EN 60664-1 |

## 10. Safety advices

Please read the following safety advices and the assembly chapter 2 before installation and keep it for future reference.

## Proper use

The IMB3-31-device is designed for the evaluation and display of sensor signals.


## Danger! Careless use or improper operation can result in

 personal injury and/or cause damage to the equipment.
## Control of the device

The panel meters are checked before dispatch and sent out in perfect condition. Should there be any visible damage, we recommend close examination of the packaging. Please inform the supplier immediately of any damage.

## Installation

The MB3-31-device must be installed by a suitably qualified specialist (e.g. with a qualification in industrial electronics).

## Notes on installation

- There must be no magnetic or electric fields in the vicinity of the device, e.g. due to transformers, mobile phones or electrostatic discharge.
- The fuse rating of the supply voltage should not exceed a value of 0.5A N.B. fuse!
- Do not install inductive consumers (relays, solenoid valves etc.) near the device and suppress any interference with the aid of RC spark extinguishing combinations or free-wheeling diodes.
- Keep input, output and supply lines separate from one another and do not lay them parallel with each other. Position "go" and "return lines" next to one another. Where possible use twisted pair. So, you receive best measuring results.
- Screen off and twist sensor lines. Do not lay current-carrying lines in the vicinity. Connect the screening on one side on a suitable potential equaliser (normally signal ground).
- The device is not suitable for installation in areas where there is a risk of explosion.
- Any electrical connection deviating from the connection diagram can endanger human life and/or can destroy the equipment.
- The terminal area of the devices is part of the service. Here electrostatic discharge needs to be avoided. Attention! High voltages can cause dangerous body currents.
- Galvanic isolated potentials within one complex need to be placed on an appropriate point (normally earth or machines ground). So, a lower disturbance sensibility against impacted energy can be reached and dangerous potentials, that can occur on long lines or due to faulty wiring, can be avoided.


## 11. Error elimination

|  | Error description | Measures |
| :---: | :---: | :---: |
| 1. | The unit permanently indicates overflow. | - The input has a very high measurement, check the measuring circuit. <br> - With a selected input with a low voltage signal, it is only connected on one side or the input is open. <br> - Not all of the activated supporting points are parameterised. Check if the relevant parameters are adjusted correctly. |
| 2. | The unit permanently shows underflow. | - The input has a very low measurement, check the measuring circuit. <br> - With a selected input with a low voltage signal, it is only connected on one side or the input is open. <br> - Not all of the activated supporting points are parameterised. Check if the relevant parameters are adjusted correctly. |
| 3. | The word HELP lights up in the 7-segment display. | - The unit has found an error in the configuration memory. Perform a reset on the default values and reconfigure the unit according to your application. |
| 4. | Program numbers for parameterising of the input are not accessible. | - Programming lock is activated. <br> - Enter correct code. |
| 5. | ERRI lights up in the 7-segment display | - Please contact the manufacturer if errors of this kind occur. |
| 6. | The device does not react as expected. | - If you are not sure if the device has been parameterised before, then follow the steps as written in chapter 6. and set it back to its delivery state. |

