

Force

Compression force transducer up to 1,000 kN Model F1211

WIKA data sheet FO 51.10

Applications

- Plant engineering and production lines
- Measuring and inspection equipment
- Special equipment and machinery construction
- Press in forces and axial joining forces monitoring

Special features

- Measuring ranges 0 ... 1 kN up to 0 ... 1,000 kN
- For compression force measurements
- Simple force introduction, easy installation
- Protection class IP67
- Relative linearity error 0.3 % F_{nom} (0.1 % F_{nom} optional)



Compression force transducer, model F1211

Description

Compression transducers are used to determine compression forces in a wide range of applications and are suitable for static and dynamic measurement tasks.

Due to their compact design, the force transducers F1211 are used in industrial applications and in the laboratory and test field. The spherical calotte (spherical load application button) allows for a very simple force introduction. Standard mounting of the force transducer is horizontal or vertical.

They are splash-proof and and work with very great reliability under extreme conditions.

Note

In order to avoid overloading, it is advantageous to connect the compression force transducer electrically during installation and to monitor the measured value.

The force to be measured must be applied concentrically and free of transverse force. The force transducer has to be mounted on a level surface.

Specific information

- Calibration control 100 % signal
- Drag chain suitable
- Suitable load plates, see accessories
- 6-wire connection
- Relative linearity error 0.1% F_{nom}

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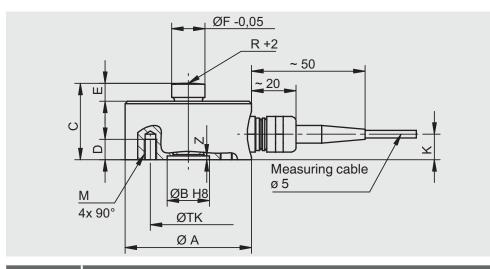


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Technical data in accordance with VDI/VDE/DKD 2638

Model F1211				
Rated force F _{nom} kN	1, 2, 5, 10, 20, 50, 100, 200, 500, 1,000			
Relative linearity error d _{lin}	$\pm 0.3 \% F_{nom}$ (optional < $\pm 0.1 \% F_{nom}$)			
Relative creep, 30 min.	< ±0.08 % F _{nom} (optional < ±0.06 % F _{nom})			
Temperature effect on zero signal TK ₀	< ±0.06 %/10 K (optional < ±0.05 %/10 K)			
Temperature effect on characteristic value TK_{C}	$< \pm 0.07 $ %/10 K (optional $< \pm 0.05 $ %/10 K)			
Force limit FL	150 % F _{nom}			
Breaking force F _B	> 300 % F _{nom}			
Permissible oscillation stress acc. to DIN 50100 $\mathrm{F_{rb}}$	70 % F _{nom}			
Rated displacement s _{nom}	< 0.15 mm			
Material	Stainless steel			
Rated temperature range B _{T, nom}	-10 +70 °C			
Operating temperature range $B_{T, G}$	-30 +80 °C			
Storage temperature range B _{T, S}	-50 +95 °C			
Reference temperature T _{ref}	23 °C			
Output signal (rated output) C _{nom}	2.0 mV/V			
Relative error of characteristic value ${\rm d}_{\rm C}$	$< \pm 0.3 \% F_{nom}$ (optional $< \pm 0.1 \% F_{nom}$)			
Input-/output resistance R _e /R _a	350 Ω			
Insulation resistance	>2 GΩ			
Electrical connection Standard Option	Cable 3 m, 4-wire 6-wire, drag chain suitable			
Rated range of excitation voltage B _{U, nom}	DC 2 12 V (max. 15 V) for mV/V			
Supply voltage Standard Option	DC 12 28 V For optional integrated or cable amplifier mA/V			
Option	Integrated or cable amplifier 0(4) 20 mA DC 0 10 V Integrated amplifier for 20 kN up to 1,000 kN possible			
Protection (acc. to IEC/EN 60529)	IP67			
Calibration control (Option)	100 % signal (detuning of the measuring bridge possible via integrated, switchable shunt resistor)			
Weight in kg 1, 2, 5, 10 kN 20, 50 kN 100 kN 200 kN 500 kN 1,000 kN	0.4 1.5 3.0 3.2 7.0 8.3			

Dimensions in mm



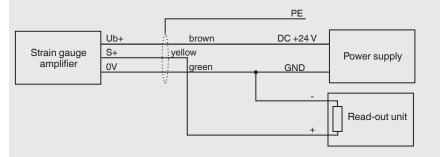
Rated	Dimensions in mm										
force in kN	øA	øB	С	D	Е	øF	М	øTK	R	Z	К
1, 2, 5, 10	49.5	34	30	8	7	13	M 5	42	60	1.3	10
20, 50	89.5	55	48	14	12.5	25	M 10	70	100	2.5	17.5
100, 200	115	68	60	16	12.5	32	M 12	90	180	1.8	23
500, 1,000	150	97	80	20	15	44	M 16	125	270	4.5	32

Pin assignment

Electrical connection			
Excitation voltage (+) 1)	Brown		
Excitation voltage (-) 1)	Green		
Signal (+) 1)	Yellow		
Signal (-)	White		
Control	Grey		
Screen 🖲	Screen		

1) Also for force transducers with integrated amplifiers 0(4) ... 20 mA, 0 ... 10 V, 3-wire system

Pin assignment for integrated amplifier or cable amplifier



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The specifications given in this document represent the state of engineering at the time of publishing. We reserve the right to make modifications to the specifications and materials.

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